GSILIB解析例

L2P(Y)-L2C サイクルシフト補正

#### ※L2P(Y)-L2Cサイクルシフト

近代化GPSではL2P(Y)とL2Cを、準天頂衛星ではL2Cを送信している。 L2P(Y)とL2Cの間で1/4サイクルのずれが存在し、位相を揃えるための 符号が受信機種によって異なる。

→異機種受信機間におけるL2P(Y)、L2Cを併用した解析で補正が必要

解析条件

- ▶ 観測時間:2014年9月13日0時30分~5時30分
- ≻ 観測点:
  - つくば長距離GNSS比較基線場(No.02, No.10)
- ➢ 受信機: No.02 JAVAD TRE\_G3T DELTA

No.10 - Trimble NetR9

- ▶ 測位方式:キネマティック
- ▶ 衛星系:GPS、QZSS
- ➢ No.02を既知点として、No.10を計算

# 手順 ※I2c\_data.zipをD:¥に展開と仮定

- 1. GSILIBのbin¥gsipost\_gui.exeを起動
- 2. [Options...]を選択
- 3. [Load]をクリックし、D:¥l2c\_data¥l2c.confを選択
- 4. [OK]を選択
- 5. [RINEX OBS: Rover]にNo.10のoファイル(tr102561.14o)、 [RINEX OBS: Base Station]にNo.02のoファイル (jv022561.14o)、[RINEX \*NAV]にNo.02のnファイル (jv022561.14n)、qファイル(jv022561.14q)を格納
- 6. [Execute]を選択し、解析実行
- 7. D:¥l2c\_dataにposファイル(tr102561.pos)が作成され、 [Plot...]を選択すれば、グラフを描画する

# データ設定画面

SSIPOST ver.1.0.0	X
Time Start (GPST) ? Time End (GPST) ? Interval   2000/01/01 ↓ 00:00:00 ↓ 2000/01/01 ↓ 0 ▼ ₽	Unit 24 H
RINEX OBS: Rover ?	+ -
D:¥l2c_data¥tr102561.14o	<b>-</b>
RINEX OBS: Base Station	$\oplus$
D:¥l2c_data¥jv022561.14o	<del>-</del> ]
RINEX *NAV/CLK, SP3, IONEX or SBS/EMS	
D:¥l2c_data¥jv022561.14n	<del>-</del>
D:¥l2c_data¥jv022561.14q	<b>-</b>
	-
Solution Dir	
D:¥l2c_data¥tr102561.pos	
	?
Plot View To KML Options Execute	<u>E</u> xit

# Options – Setting1

Options	-								×
Setting <u>1</u>	Setting2	Setting3	stics	Positic	Misc				
Position	ning Mode				Kine				
Freque	ncies				L1+	L2		-	
L2 Cod	e Priority				L2P(	Y)		-	
Solution	n Type				Forv	vard		)	
Elevatio	on Mask (°	) / SNR Ma	sk <mark>(d</mark> bHz)		15 🔻				
Rec Dy	namics/Ea	rth Tides C	orrection						
Ionosp	here Corre	ection			Broadcast 👻				
Tropos	phere Corr	rection			Saastamoinen 🔻				
Time Sy	/stem Corr	ection			OFF 🔻				
Satellite	e Ephemer	is/Clock			Broa	dcast		-	
Sat PC	/ R	ec PCV s (+PRN:	QZSSを	選折	ļ	iect Ed		RAIM F	DE
Glonas:	GPS 🔲 G s L 1 Code I	GLO 🔲 Ga Priority	alileo 🔽 (	QZSS	SI	BAS	Be	eidou	
Gionass	s L2 Code l	Priority							

# **Options – Setting2**

				x
Setting <u>1</u> Setting <u>2</u> Setting <u>3</u> Output Stat	tistics Pos	itions <u>F</u>	iles	Misc
Integer Ambiguity Resolution Method	LAMBDA		•	
Integer Ambiguity Resolution Strategy	Continuo	us	-	
GLONASS Ambiguity Resolution	ON		-	
PPP Ambiguity Resolution	OFF		-	
Min Ratio to Fix Ambiguity	3			
Min Confidence / Max FCB to Fix Amb	0.9999	0.2	ī	
Min Lock / Elevation (°) to Fix Ambiguity	0	0		
Min Fix / Elevation (°) to Hold Ambiguity	10	0	_	[ <b>T</b> .
Outage to Reset Amb/Slip Thres (m)	5	0.050	_	
Phase Cycle Shift	Table	~	-	
L2C-L2P Bias	OFF		-	
Max Age of Differential (s)	30.0			
Reject Threshold of GDOP/Innov (m)	30.0	30.0	T	
Number of Filter Iteration	1			
Baseline Length Constraint (m)	0.000	0.000	Ī	
Inter System Bias	OFF		-	
Analysys Method in Double Differencing	exc. glon	ass	-	

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## Options – Setting3

Options						×			
Setting1 Setting2 Setting3	Output Sta	atistics	Posit	ions	Files	Misc			
Phase Cycle Shift, GLONASS IFB D:¥l2c_data¥l2csft.tbl									
Options - Setting2で[Table]を指定した 合、L2Cサイクルシフトテーブルを選択 Multi Baseline Static Estimate Satellite Clock/FCB フト量を記載									
Semi-Dynamic Correction Parar	neter								
Solution Directory									
Est. Interval of ZTD (s)		7200							
Est. Interval of Trop. Gradient	(s)	43200							
Trop. Process Noise Zen/EW/N	1.00E	-( 1.0	0E-C	1.00E-(					
O-C Reject Phase/Code (sigma	)	5.0		5.0					
Fixing Probability WL/NL		0.999	90	0.99	990				
Convergence Factor of Iteratio	n	1.00E-03							

# Options – Output

Options					-				×
Setting <u>1</u>	Setting2	Setting <u>3</u>	Output	S <u>t</u> atis	tics	<u>P</u> ositi	ons	<u>Files</u>	Misc
Sol	ution Forma	at			Lat/l	.on/He	•		
Out	tput Heade	r/Processir	ng Options		ON	•	ON	•	
Tim	e Format /	# of Decin	nals		hh:m	nm:ss (	SPST	▼ 3	
Lat	itude / Long	gitude Forr	nat		ddd.	ddddd	dd		
Fiel	d Separato	r							
Dat	tum/Height				WGS	84 🔻	Ellips	soir 🔻	
Geo	oid Model				Inter	rnal			
Solu	ution for St	atic Mode			All			-	
NM	EA Interval	(s) RMC/0	GGA, GSA/	GSV	0		0		
Out	tput Solutio	n Status /	Debug Tra	ice	OFF	•	OFF		
Out	tput ISB Da	ta			OFF			<b>_</b> ]	
								]	
Out	tput L2P-L2	C Data			OFF				
Out	tput Positio	n in SINEX			OFF				

### **Options – Statistics**

Options		_				-			x			
Setting1	Setting2	Setting3	O <u>u</u> tput	S <u>t</u> ati	stics	Positi	ons	<u>F</u> iles	Misc			
Measur	Measurement Errors (1-sigma)											
Error Model User Settings 👻												
C	ode/Carrier-	Phase Erro	r Ratio L1		100.	0						
C (	ode/Carrier-	Phase Erro	r Ratio L2		100.	0						
C	ode/Carrier-	Phase Erro	r Ratio L5		100.	0						
G	arrier-Phase	Error a+b	/sinEl (m)		0.003 0.003			03				
C	ode Error Ra	atio (no DCE	3)		10.0							
Ci	arrier-Phase	Error/Base	line (m/10	)km)	0.00	0						
De	oppler Frequ	iency (Hz)			10.0	00						
Process	Noises (1-s	igma/sqrt(s	s))									
R	eceiver Acce	l Horiz/Ver	tical (m/s2	)	1.00	E-01	1.0	0E-02				
Ca	Carrier-Phase Bias (cycle) 1.00E-04											
Ve	ertical Ionos	pheric Dela	y (m/10kn	1)	1.00	E-03						
Ze	nith Tropos	pheric Dela	y (m)		1.00	E-04						
Ca	arrier-Phase	Inter-Syst	em Bias (n	n)	0.00	E+00						

#### **Options – Positions**

0								x	J
	Setting <u>1</u>	Setting2	Setting3	O <u>u</u> tput	Statistics	Positions	Files	Misc	
	Rover								
	Lat/Lon/	Height (de	g/m) 🔻						
	90.0000	00000	0.000	000000	-	6335367.62	85		
	Anter	nna Type (*	*: Auto)		Delta-E/I	N/U (m)			
					• 0.0000	0.0000	0.000	D	
	Receiver	Туре	Trimb	le NetR9					
	Base Sta RINEX H	ition leader Post	tion ▼	L20 信相	サイク 機名にす	ルシフト <del>-</del> する	テーフ	ブル(こ言	記載された受
		20017	Auto)	<u>デ</u>	ーブルに	こ記載が	ない	受信機	は補正しない
		патуре (	. Adtoj		- 0.0000	0.0000	0.000	0	
	Receiver	Туре	JAVA	D TRE_G3	3T DELTA				
	Station P	osition File						_	
							=	ı	

#### **Options – Files**

Options							×
Setting	Setting2	Setting3	O <u>u</u> tput	S <u>t</u> atistics	Positions	<u>Files</u>	Misc
Satellite	/Receiver Ar	ntenna PCV	File ANTE	EX/NGS PCV		Ξ	E
Geoid D	ata File						
Ionosph	ere Data File	5					
	iere batarrik	-					
DCB Da	ta File						E
ISB Dat	a File						E
Google	Earth Exe Fil	e					
BIPM Ci	cular T File						
EOP Da	ta File						Ē
OTL BLO	) File						

# Options – Misc

(	Options								×
ſ	Setting1	Setting	2 Setting3	O <u>u</u> tput	S <u>t</u> ati	stics	Positions	Files	Misc
	T	ime Interp	olation of Ba	ase Station	Data	OFF		•	
	D	GPS/DGNS	S Correction	ns		SBA	S	-	
	S	BAS Satelli	te Selection	(0: All)		0			
	RJ	INEX Opt (	Rover)						
	RJ	INEX Opt (	Base)						
	s	Station ID I	ist	Rover	s		Base Statio	ns	
	;	? : Keyw File Pa	ords in ath		_	*		*	
	#	#: Comm List	ient in						
						Ŧ		$\nabla$	
I									

# 解析結果(サイクルシフト補正あり)

Options – Setting2 でPhase Cycle shift [Table] を選択



# 解析結果(サイクルシフト補正なし)

Options – Setting2 でPhase Cycle Shift [OFF] を選択

